

MODBUS-RTU for 200SCH202BASE 2EV

MODBUS-RTU protocol specifications for LAN control of 200SCH202BASE2EV series devices

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READ AND KEEP

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1: GENERAL DESCRIPTION

1.1

MODBUS PROTOCOL

The data communication system based on Modbus protocol allows to connect up to 247 devices in a common RS485 line with standard format and communication mode.

Communication takes place in half duplex by frame (transmitted continuously); only master (PC , PLC ...) can start polling with slaves as question/answer (only one slave addressed) and the polled slave answers. The slave answers after a minimum pause of 3,5 characters between received frame and the one to be transmitted.

Also broadcast communication mode exists where the master send a request to all the slaves simultaneously, and they give no answer back; this mode it's not available with this controller.

The data serial transmission mode implemented on the controller is RTU type (Remote Terminal Unit), where data are exchanged in binary format (8 bit characters).

1.2

SERIAL CONFIGURATION

Linea seriale:	RS485
Baud rate:	300, 600, 1200, 2400, 4800, 9600, 14400, 19200, 38400
Lunghezza dati:	8 bit
Parità:	nessuna, pari o dispari

Trasmissione seriale dei caratteri in formato RTU

Start	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0	Parità (optional)	Stop
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Each message (Frame) is made, based on MODBUS-RTU standard, by the following parts:

Start	Device address	Function code	Data	CRC16		Stop
pause (3.5 times the character transmission period)	Byte	Byte	n x Byte	LSByte	MSByte	pause (3.5 times the character transmission period)

- **Start / Stop :**
Message starts with pause higher than 3.5 times the character transmission period. See chap. 4.1 for further clarifications.
- **Device address:**
Device address with whom the master established the polling; it's a value between 1 and 247. Address 0 is reserved to the broadcast, message sent to all slave devices (not active on this controller). RS485 line allows to connect together up to 32 devices (1 Master + 31 slaves), but with appropriate "bridges" or relay devices it is possible to use the whole logical addressing field.
- **Function Code:**
Code of the function to be execute or already executed; On device are active codes 0x03 (register reading), 0x06 (single register writing) and 0x2B/0x0E (identification data reading).
- **Data:**
Data that must be exchanged.
- **CRC16:**
Error checking field based on CRC16 algorithm. CRC16 is calculated on the whole message by the master device which is transmitting and attached to the message itself. The slave, at the end of reception, calculates CRC16 on the message and compares it with the value learnt by the master; if the values do not match, the message will be considered not valid and will be discarded without sending any answer to the master.
The following fragment of C code shows the CRC16 calculation mode:

```

unsigned int CRC16
void Modbus_CRC(unsigned char *Frame, unsigned char FrameLength)
{
    unsigned char ByteCount;
    unsigned char i;
    unsigned char bit_lsb;
    CRC16 = 0xFFFF;
    for (ByteCount=0;ByteCount<FrameLength;ByteCount++)
    {
        CRC16^=Frame[ByteCount];
        for (i=0;i<8,i++)
        {
            bit_lsb = CRC16 & 0x0001;
            CRC16 = CRC16>>1;
            if (bit_lsb == 1)
                CRC16 ^= 0xA001;
        }
    }
}

```

1.4

MESSAGES SYNCHRONIZATION

Message synchronization between transmitter and receiver is made placing a pause on the messages at least 3.5 times the character transmission period. If the receiver does not receive any Byte for 3.5 times the character transmission period, consider the last message completed and set the next Byte received as the first one of a new message.

The slave, once received the complete message, decodes it and, if there are no errors, sends the answer message to the master. To send the answer, slave keeps RS485 line busy, wait a pause of 3.5 times the character transmission period, send the complete message, wait 3.5 times the character transmission period and then release the RS485 line.

The master unit will have to consider these periods to avoid risks of transmission overlap; in particular must be set a proper answer reception time-out before starting a new transmission (typical time-out value: 500msec or higher, for a baud rate = 9600).

1.5

ERROR MESSAGES (EXCEPTIONS)

The device, if not possible to complete the required operation, answers with an error message, in the following format:

<i>Device address</i>	<i>Function Code</i>	<i>Exception Code</i>	<i>CRC16</i>	
Byte	Byte	Byte	LSByte	MSByte

- **Device address:**
Address of slave device answering
- **Function Code:**
Function code MSb =1 (to show exception); i.e. 0x83 (for 0x03 reading) or 0x86 (for 0x06 writing)
- **Exception Code:**
Exception codes handled by the device are the following:

<i>Exception code</i>	<i>Description</i>	<i>Exception cause</i>
0x01	Function not implemented	A function code not available was requested, different from 0x03, 0x06 and 0x2B/0x0E.
0x02	Address not valid	It's generated in several situations: <ul style="list-style-type: none"> - a not implemented register has been requested (or a not-existing area) - a reading of a number of registers that goes further on the implemented area has been requested (starting from requested address) - tried to write on a read-only area
0x03	Value not valid for datum	It's generated in several situations: <ul style="list-style-type: none"> - message 0x2B/0x0E DeviceIdCode is not correct - has been tried to write a parameter with an out of range value

Error control field based on the CRC16 algorithm.

Note:

In case the device identifies in the received message an error on format or in CRC16, the message is discarded (considered not valid) and no answer is sent.

2: COMMANDS DESCRIPTION

All the registers, to equalize the interpretation, are handled in a Word format (16 bit), even if an 8-bit parameter is contained.

2.1

REGISTER READING (0x03)

Format of command sent by the Master:

<i>Device address</i>	<i>Function Code</i>	<i>Register address</i>		<i>Number of registers</i>		<i>CRC16</i>	
Byte	Byte	MSByte	LSByte	MSByte	LSByte	LSByte	MSByte

- **Device address:**
Address of slave device to be polled
- **Function Code:**
Function code to be executed, in this case register reading (0x03)
- **Register address:**
Starting register address for reading expressed with two Bytes; (MSByte) and (LSByte).
- **Number of registers:**
indicates the number of Word required from the starting address. If a number of registers more than 1 is requested, the answer message will provide all the registers required with consecutive addresses starting from the address shown on the "register address" field.
The number of registers to read is expressed on two Bytes, particularly for this controller (MSByte) must always be 0x00 and (LSByte) with range 1-10.
- **CRC16:**
Error control field based on the CRC16 algorithm.

Format of answer message from slave:

<i>Device address</i>	<i>Function Code</i>	<i>Bytes of datum No.</i>	<i>Datum 1</i>		<i>Datum 2</i>		<i>Datum n</i>		<i>CRC16</i>	
Byte	Byte	Byte	MSByte	LSByte	MSByte	LSByte	MSByte	LSByte	LSByte	MSByte

- **Device address:**
Address of slave device answering
- **Function Code:**
Function code to be answered to, in this case register reading (0x03)
- **Bytes' number of datum:**
Contains the total Bytes number of data.
Consider that the Bytes' number of datum is the double of the number of registers (because we talk about word). I.e. if in the polling message 2 registers are requested, in the answer message Bytes' number of datum must be set as 4.
- **Datum n :**
Contains data sequences each expressed on two Bytes; (MSByte) and (LSByte).
- **CRC16:**
Error control field based on the CRC16 algorithm.

2.2

SINGLE REGISTER WRITING (0x06)

Format of command sent by the Master:

<i>Device address</i>	<i>Function Code</i>	<i>Register address</i>		<i>Datum</i>		<i>CRC16</i>	
Byte	Byte	MSByte	LSByte	MSByte	LSByte	LSByte	MSByte

- **Device address:**
Address of slave device to be polled
- **Function Code:**
Function code to be executed, in this case single register writing (0x06)
- **Register address:**
address of register to write expressed with two Bytes; (MSByte) and (LSByte).
- **Data:**
Value to be assigned to the register expressed with two Bytes; (MSByte) and (LSByte).
- **CRC16:**
Error control field based on the CRC16 algorithm.

Format of answer message from slave:

<i>Device address</i>	<i>Function Code</i>	<i>Register address</i>		<i>Datum</i>		<i>CRC16</i>	
Byte	Byte	MSByte	LSByte	MSByte	LSByte	LSByte	MSByte

The answer message is a simple echo of the polling message to confirm that the variable has been modified.

Format of command sent by the Master:

<i>Device address</i>	<i>Function Code</i>	<i>MEI type</i>	<i>Read Device Id Code</i>	<i>Object Id</i>	<i>CRC16</i>	
Byte	Byte	Byte	Byte	Byte	LSByte	MSByte

- **Device address:**
Address of slave device to be polled
- **Function Code:**
Function code to be executed, in this case identification data reading (0x2B)
- **MEI type:**
Modbus Encapsulated Interface type: it must be 0x0E.
- **Read Device Id Code:**
Indicates the access type to data: it must be 0x01.
- **Object Id:**
Indicates the starting object for data reading (range: 0x00 – 0x02).
- **CRC16:**
Error control field based on the CRC16 algorithm.

Format of answer message from slave:

<i>Device address</i>	<i>Function code</i>	<i>MEI Type</i>	<i>Read Device Id Code</i>	<i>Confor mity level</i>	<i>More Follows</i>	<i>Next Object Id</i>	<i>Number Of Object</i>	<i>Object Id (n)</i>	<i>Object Length (n)</i>	<i>Object Value (n)</i>	<i>CRC16</i>	
Byte	Byte	Byte	Byte	Byte	Byte	Byte	Byte	Byte	Byte	ASCII String	LSByte	MSByte

- **Device address:**
Address of slave device answering
- **Function Code:**
Function code to be executed, in this case identification data reading (0x2B)
- **MEI type:**
Modbus Encapsulated Interface type: it must be 0x0E.
- **Read Device Id Code:**
Indicates the access type to data: it must be 0x01.
- **Conformity level:**
indicates the slave conformity level: it is always 0x01.
- **More Follows:**
indicates the number of additional transactions requested: it is always 0x00.
- **Next Object Id:**
indicates the object that has to be requested in the eventual following transaction: it is always 0x00
- **Number Of Object:**
number of objects that follow (1, 2 o 3).

- **List of:**
 - **Object Id:**
current object number .
 - **Object Length:**
length of following string.
 - **Object Value:**
ASCII string that contains the identification information.
- **CRC16:**
Error control field based on the CRC16 algorithm.

Reading example of all controllers identification information with software ECP202 2EV rel. 0 (address 1)

Demand message: (01 2B 0E 01 00 70 77)

- **Device address:** 0x01
- **Function code:** 0x2B
- **MEI type:** 0x0E
- **Read DeviceIdCode:** 0x01
- **ObjectId:** 0x00
- **CRC16:** to be calculated on previous values

Answer message:

- **Device address:** 0x01
- **Function code:** 0x2B
- **MEI type:** 0x0E
- **Read DeviceIdCode:** 0x01
- **Conformity level:** 0x01
- **More Follows:** 0x00
- **Next ObjectId:** 0x00
- **Number Of Object:** 0x03
- **ObjectId:** 0x00
- **Object Length:** 0x04
- **Object Value:** 'PEGO' (Vendor Name field)
- **ObjectId:** 0x01
- **Object Length:** 0x08
- **Object Value:** 'ECP2022E' (Product Code field)
- **ObjectId:** 0x02
- **Object Length:** 0x03
- **Object Value:** '000' (Revision field)
- **CRC16:** to be calculated on previous values

3: REGISTERS AND ADDRESSES DESCRIPTION

Each register has a 16 bit dimension. It has been formed some blocks of variables (each with a different MSByte address) basing on the the type of these variables. In the followings paragraphs are described in the detail all the available blocks and, for each block, the implemented variables.

At the beginning of each table it has been indicated in the first row if its data could be only read (READ-ONLY) or written and read (READ/WRITE).

TABLE COLUMNS DESCRIPTION:

- **Register :**
It indicates the register address that has to be used in the structure of Modbus command for reading or writing the data into device. It is expressed on two Bytes: (MSByte) and (LSByte).
- **Description :**
Description of the register and possible corresponding programming variable of the device.
- **Meaning and Bytes range:**
Dimension (MSByte and LSByte), allowed range and notes about register.
- **U.M. :**
Unit of measure of datum contained in the register.
- **Conv. :**
Values contained in the registers that represent signed variables require a conversion and they are marked from **X** sign in the following column.
Conversion procedure:
 - If the value contained in the register is included between 0 and 32767, it represents a positive or null number (the results is the value itself)
 - If the value contained in the register is included between 32768 and 65535, it represents a negative number (the results is the register value - 65536)
- **Molt :**
It indicates the multiplication factor that has to be mapped to register's datum and that coupled to columns U.m and Conv permits the right interpretation of the value to convert.
Esempi:
A datum (**0x0012**) = 18 with Molt =**0,1** / U.m= °C / Conv=C corresponds to a temperature of (18x0,1)= **1,8 °C**
A datum (**0xFFFF0**) = 65520 with Molt =**0,1** / U.m= °C / Conv=C corresponds to a temperature [(65520 – 65536) x0,1] = **-1,6 °C**
A datum (**0x0078**) = 120 with Molt =**1** / U.m= **min** / Conv=C corresponds to a time of (120x1)= **120 minutes**
A datum (**0x0014**) = 20 with Molt =**0,1** / U.m= °C / Conv=C corresponds to a temperature of (20x0,1)= **2,0 °C**

3.1

ANALOG INPUTS

READ-ONLY						
Register	Description	Bytes meaning and range		U.M.	Conv	Molt
256	Ambient temperature	MSByte LSByte	Resolution 0,1°C range: -45°C .. +99°C Values > +99°C indicate broken probe	°C	X	0,1
257	Auxiliary probe temperature	MSByte LSByte	Resolution 0,1°C range: -45°C .. +99°C Values > +99°C indicate broken probe	°C	X	0,1

258	Evaporator 1 Temperature	MSByte LSByte	Resolution 0,1°C range: -45°C .. +99°C Values > +99°C indicate broken probe	°C	X	0,1
259	Evaporator 2 temperature	MSByte LSByte	Resolution 0,1°C range: -45°C .. +99°C Values > +99°C indicate broken probe	°C	X	0,1

3.2

PARAMETERS

READ / WRITE						
Register	Description	Bytes meaning and range		U.M.	Conv	Molt
768	temperature set point	MSByte LSByte	0.1 °C steps, with sign range: LSE..HSE	°C		0,1
769	r0 temperature differential	MSByte LSByte	0.1 °C steps range: 0.2..10.0 °C	°C		0,1
770	d0 defrosting period	MSByte LSByte	1 hour steps range: 0..24 hours (0 = disabled)	hours		1
771	dd2 Delayed defrost for the second evaporator	MSByte LSByte	1 second steps range: 0..10 seconds (0 = disabled)	seconds		1
772	d21 end-of-defrosting 1 temperature	MSByte LSByte	1 °C steps, with sign range: -35..+45 °C	°C	X	1
773	d22 end-of-defrosting 2 temperature	MSByte LSByte	1 °C steps, with sign range: -35..+45 °C	°C	X	1
774	d31 max defrosting 1 duration	MSByte LSByte	1 minute steps range: 1..240 minutes	min		1
775	d32 max defrosting 2 duration	MSByte LSByte	1 minute steps range: 1..240 minutes	min		1
776	d7 dripping duration	MSByte LSByte	1 minute steps range: 0..10 minutes (0 = disabled)	min		1
777	F5 fans stop duration post defrosting	MSByte LSByte	1 minute steps range: 0..10 minutes (0 = disabled)	min		1
778	A1 temperature alarm minimum threshold	MSByte LSByte	1 °C steps, with sign range: -45°C..(A2-1°C)	°C	X	1

779	A2 temperature alarm maximum threshold	MSByte LSByte	1 °C steps, with sign range: (A1+1°C)..+99°C	°C	X	1
780	Ar Temperature alarms related to the set point	MSByte LSByte	0 = Temp. alarm absolute value 1 = Temp. alarm related to setpoint	num		1
781	dFr Real time defrost enable	MSByte LSByte	0 = disabled 1 = enabled	num		1
782	dF1 Defrost time 1	MSByte LSByte	10 minute steps range: 0..143	min		10
783	dF2 Defrost time 2	MSByte LSByte	10 minute steps range: 0..143	min		10
784	dF3 Defrost time 3	MSByte LSByte	10 minute steps range: 0..143	min		10
785	dF4 Defrost time 4	MSByte LSByte	10 minute steps range: 0..143	min		10
786	dF5 Defrost time 5	MSByte LSByte	10 minute steps range: 0..143	min		10
787	dF6 Defrost time 6	MSByte LSByte	10 minute steps range: 0..143	min		10
788	tdS Day start programming	MSByte LSByte	10 minute steps range: 0..143	min		10
789	tdE Day end programming	MSByte LSByte	10 minute steps range: 0..143	min		10
790	F3 fans status with stopped compressor	MSByte LSByte	range: 0..2 0 = fans in continuous gear 1 = run when compressor is working 2 = Fans disabled	num		1
791	F4 fans stop in defrosting	MSByte LSByte	range: 0..1, (1 = stopped fans)	num		1
792	F6 Evaporator fans activation for air recirculation.	MSByte	1 minute steps range: 0... 240 min 0 = function not activated	min		1

793	F7 Evaporator fans duration for air recirculation	MSByte LSByte	1 second steps range: 0..240 sec.	sec		1
794	dE1 evaporator 1 probe exclusion	MSByte LSByte	range: 0..1, (1 = probe excluded)	num		1
795	dE2 evaporator 2 probe exclusion	MSByte LSByte	range: 0..1, (1 = probe excluded)	num		1
796	AUE Auxiliary probe enable	MSByte LSByte	range: 0..3, (0 = probe excluded)	num		1
797	dPo Defrost at Power On	MSByte	0 = disabled 1 = defrost at power-on (if possible)	num		1
798	dSE Smart defrost	MSByte LSByte	0 = disabled 1 = enabled	num		1
799	dSt Smart defrost Setpoint (if dSE=1)	MSByte	1 °C steps range: -30..30 °C	°C	X	1
800	dFd Display viewing during defrost	MSByte LSByte	0 = current temperature 1 = temperature at the beginning of the defrost 2 = "DEF"	num		1
801	ALd temperature alarm signaling delay	MSByte LSByte	1 minutes steps range: 0..240 minutes	min		1
802	AtE Temperature alarm enabling	MSByte LSByte	0 = always enabled 1 = disabled in case of standby 2 = disabled if door switch active 3 = disabled if standby or door switch active	num		1
803	C1 compressor re-starting delay	MSByte LSByte	1 minute steps range: 0..15 minutes (0 = disabled)	min		1
804	CE1 Duration of compressor ON time in the case of faulty ambient probe	MSByte LSByte	1 minute steps range: 0..240 minutes (0 = disabled)	min		1
805	CE2 Duration of compressor OFF time in the case of faulty ambient probe	MSByte LSByte	1 minute steps range: 5..240 minutes	min		1

806	CA1 ambient probe calibration	MSByte LSByte	0.1 °C steps, with sign range: -10.0..+10.0 °C	°C	X	0,1
807	CA2 Auxiliary probe calibration	MSByte LSByte	0.1 °C steps, with sign range: -10.0..+10.0 °C	°C	X	0,1
808	doC compressor safety time for door switch	MSByte LSByte	1 minute steps range: 0..5 minutes (0 = disabled)	min		1
809	tdo compressor restart time after door opening	MSByte LSByte	1 minute steps range: 0..240 minutes (0 = disabled)	min		1
810	tlo Cell light alarm signal and display delay time	MSByte LSByte	1 minute steps range: 0..240 minutes (0 = disabled)	min		1
811	FSt fans blockage temperature	MSByte LSByte	1 °C steps, with signs range: -45..+99 °C	°C	X	1
812	Fd Differential on fans blockage	MSByte LSByte	1 °C steps range: 1..10 °C	°C		1
813	LSE temperature set-point minimum limit	MSByte LSByte	1 °C steps, with sign range: -45°C..(HSE-1°C)	°C	X	1
814	HSE temperature set-point maximum limit	MSByte LSByte	1 °C steps, with sign range: (LSE+1°C)..+99°C	°C	X	1
815	StA Temperature setting for aux. relay	MSByte LSByte	1 °C steps range: -45..99 °C	°C	X	1
816	nSC Correction factor for the SET button during night operation	MSByte LSByte	0.1 °C steps range: -20.0..20.0 °C	°C		0,1
817	bEE Buzzer enable	MSByte LSByte	0 = disabled 1 = enabled	num		1

3.2a

PARAMETERS

READ-ONLY						
Registro	Descrizione	Significato e range Bytes		U.M.	Conv	Molt
512	mOd Thermostat functioning mode	MSByte LSByte	0 = Cold function 1 = Hot function	num		1
513	nrE Number of evaporators	MSByte LSByte	1 = 1 evaporator 2 = 2 evaporators	num		1
514	d1 Defrost type	MSByte LSByte	0 = heaters 1 = hot gas 2 = heater with temperature control	num		1
515	In1 Input 1 setting	MSByte LSByte	range: -8 .. +8 (0=disabled)	num		1
516	In2 Input 2 setting	MSByte LSByte	Like In1.	num		1
517	In3 Input 3 setting	MSByte LSByte	Like In1.	num		1
518	DO1 Output relay 1 control	MSByte LSByte	range: -6 .. +6 (0=disabled)	num		1
519	DO2 Output relay 2 control	MSByte LSByte	Like AU1.	num		1
520	DO3 Output relay 3 control	MSByte LSByte	Like AU1.	num		1
521	DO4 Output relay 4 control	MSByte LSByte	Like AU1.	num		1
522	DO5 Output relay 5 control	MSByte LSByte	Like AU1.	num		1
523	DO6 Output relay 6 control	MSByte LSByte	Like AU1.	num		1
524	HACCP_E last temperature alarm	MSByte LSByte	5 : Alarm EH 6: Alarm EL	num		1
525	HACCP_T last temperature alarm peak value	MSByte LSByte	Resolution 0,1°C range: -45°C .. +99°C	°C	X	0,1

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526	HACCP_y Year of the last temperature alarm	MSByte LSByte	Resolution 1 range: 0 .. 99	num	1
527	HACCP_M Month of the last temperature alarm	MSByte LSByte	Resolution 1 range: 1 .. 12	num	1
528	HACCP_d Day of the last temperature alarm	MSByte LSByte	Resolution 1 range: 1 .. 31	num	1
529	HACCP_h Hour of the last temperature alarm	MSByte LSByte	Resolution 1 range: 0 .. 23	num	1
530	HACCP_m Minutes of the last temperature alarm	MSByte LSByte	Resolution 1 range: 0 .. 59	num	1
531	HACCP_t Time (hours) the last temperature alarm lasted	MSByte LSByte	Resolution 1 range: 0 .. 99	num	1
532	HACCP_C Number of temperature alarm events	MSByte LSByte	Resolution 1 range: 0 .. 99	num	1

3.2b

PARAMETERS REAL-TIME CLOCK

READ/WRITE						
<i>Register</i>	<i>Description</i>	<i>Bytes meaning and range</i>		<i>U.M.</i>	<i>Conv</i>	<i>Molt</i>
1024	Minute	MSByte LSByte	Range: 0..59	Min.		1
1025	Hour	MSByte LSByte	Range: 0..23	Hour		1
1026	Year	MSByte LSByte	Range: 0..99	num		1
1027	Month	MSByte LSByte	Range: 1..12	num		1
1028	Day	MSByte LSByte	Range: 1..28, 1..29, 1..30, 1..31 (according to the month and year)	num		1

3.3

INPUTS / OUTPUTS / ALARMS STATUS

READ-ONLY							
Register	Description	Bytes meaning			U.M.	Conv	Molt
1280	output status	MSByte	bit 7 (MSb)	Not used	num		1
			bit 6	Not used			
			bit 5	Not used			
			bit 4	Not used			
			bit 3	Hot resistance relay			
			bit 2	Night relay			
			bit 1	Standby relay			
			bit 0 (LSb)	Pumpdown relay			
		LSByte	bit 7 (MSb)	Aux for StA relay			
			bit 6	Aux for button relay			
			bit 5	Alarm relay			
			bit 4	Defrost 2 relay			
			bit 3	Defrost 1 relay			
			bit 2	Cold room light			
			bit 1	Fans relay			
bit 0 (LSb)	Compressor relay						

READ-ONLY							
Register	Description	Bytes meaning			U.M.	Conv	Molt
1281	input status	MSByte	bit 7 (MSb)	Not used	num		1
			bit 6	Not used			
			bit 5	Not used			
			bit 4	Not used			
			bit 3	Not used			
			bit 2	Not used			
			bit 1	Not used			
			bit 0 (LSb)	Bypass defrost input			
		LSByte	bit 7 (MSb)	Night digital input (energy saving)			
			bit 6	Pump-down input			
			bit 5	Remote Stop defrost			
			bit 4	Remote Start defrost			
			bit 3	Remote Stand-by			
			bit 2	Man in cold room alarm (E8)			
			bit 1	Door-switch			
bit 0 (LSb)	Compressor protection (EC)						

READ-ONLY							
Register	Description	Bytes meaning			U.M.	Conv	Molt
1282	alarms status	MSByte	bit 7 (MSb)	Not used	num		1
			bit 6	Not used			
			bit 5	Not used			
			bit 4	Not used			
			bit 3	Battery alarm (E6)			
			bit 2	Light alarm (E9)			
			bit 1	Compressor protection alarm (Ec)			
			bit 0 (LSb)	Man in room alarm (E8)			
		LSByte	bit 7 (MSb)	Open door alarm (Ed)			
			bit 6	Low temperature alarm (EL)			
			bit 5	High temperature alarm (EH)			
			bit 4	Auxiliary probe fault (E3)			
			bit 3	EEPROM error(E2)			
			bit 2	Evaporator 2 probe fault (Eu2)			
			bit 1	Evaporator 1 probe fault (Eu1)			
bit 0 (LSb)	Ambient probe fault (E0)						

3.4

DEVICE STATUS

READ / WRITE							
Register	Description	Bytes meaning			U.M.	Conv	Molt
1536	device status	MSByte	bit 7 (MSb)	Not used	num		1
			bit 6	Not used			
			bit 5	Not used			
			bit 4	Not used			
			bit 3	Not used			
			bit 2	Defrost forcing enabling			
			bit 1	Modific. enabling of cold room light status			
			bit 0 (LSb)	Modific. enabling of stand-by status			
		LSByte	bit 7 (MSb)	Not used			
			bit 6	Not used			
			bit 5	Not used			
			bit 4	Not used			
			bit 3	Not used			
			bit 2	Defrost forcing 1 = defrost 0 = non-defrost			
bit 1	Cold room light key status 1 = active cold room light 0 = non-active cold room light						
bit 0 (LSb)	Stand-by status 1 = stand-by 0 = ON						

For asking the modification of one of device status bits, the master has to send into LSByte the requested value for the bit and into MSByte the corresponding bit set to 1. i.e.: for stand-by status forcing, the master has to send MSByte = 00000001 and LSByte = 00000001. For disabling the cold room light, the master has to send MSByte = 00000010 and LSByte = 00000000.

4: GLOSSARY

- **Binary Number:**
It is used in computer science for the internal representation of numbers, thanks to the simplicity to physically realize an element with two state (0,1) instead an higher number, but also with the matching with the logic values TRUE and FALSE.
- **Decimal Numer:**
On decimal system all whole numbers can be represented using the ten digits that indicates the first ten natural numbers, included zero. The value of each of these digits depends on the position occupied inside the number, and it increases in powers of 10, from right to left.
- **Hexadecimal Number:**
It is part of a positional numeric system with base 16, that means it uses 16 symbols instead usual 10 of the traditional numerical deciaml system. Hexadecimal generally uses symbols from 0 to 9 and then letters from A to F, for a total 16 symbols. Conventionally an hexadecimal number is preceded by 0x (i.e. 0x03) or by H (i.e. H03).
- **bit:**
A bit is a binary digit that is one of the two symbols of numerical binary system, usually called zero (0) and one (1). It represents the definition unit of a logic state.
It's defined also as elementary unit of the information used by a computer.
- **Byte:**
It's the quantity of bit needed to define an alphanumeric character; particularly a Byte is made by a sequence of 8 bit (i.e. 10010110).
- **Word:**
Unit of measure that fixes information lenght at 16 bits that is equivalent to 2 Bytes (i.e. 10010110 01101011).
- **LSb:**
Less significant bit of a binary digit (first bit on the right of the indicated number)
- **MSb:**
Most significant bit of a binary digit (first bit on the left of the indicated number)
- **LSByte:**
Less significant Byte of a Word (Byte on the right of the indicated Word)
- **MSByte:**
Most significant Byte of a Word (Byte on the left of the indicated Word)



PEGO s.r.l.
Via Piacentina, 6/b 45030 Occhiobello ROVIGO - ITALY
Tel. +39 0425 762906 Fax +39 0425 762905
e.mail: info@pego.it – www.pego.it

AFTER-SALES ASSISTANCE CENTRE
Tel. +39 0425 762906 e.mail: tecnico@pego.it

Distributor: